

How to Define a Regional Arbitrary Geodetic Datum in Oracle Spatial

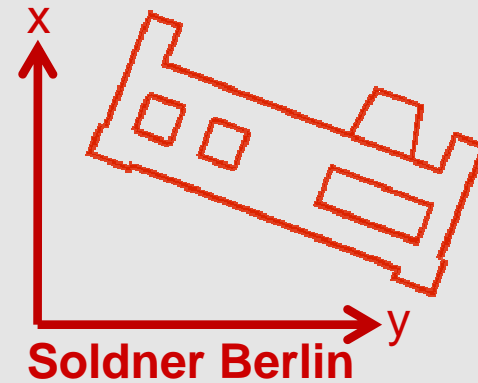
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Motivation

More and more data available from a variety of different sources.

Geoinformation referenced in different coordinate systems



Picture data based on GPS and use of the ETRS 89 as global system

Geoinformation based on terrestrial measurements and use of the Soldner Berlin 88

Combination of all -> **mash up**

- Transformation in Oracle Spatial
 - ▶ We insert a user defined system into the model of coordinate systems
 - ▶ Therefore we only need some general information on
 - Projection
 - Ellipsoid
 - Orientation with respect to a geocentric system
 - ▶ If Oracle knows our system we insert the data with respect to the system
 - ▶ Then we can transform the data into the available systems in Oracle with an simple SQL-statement.

- SQL-statement to transform local Soldner Berlin coordinates into ETRS89 coordinates

```
SELECT
  P.PKTNUM Point_number,
  SDO_CS.TRANSFORM(P.geom,83033).sdo_point.x X,
  SDO_CS.TRANSFORM(P.geom,83033).sdo_point.y Y,
FROM
  SOLDNER_BERLIN P
```

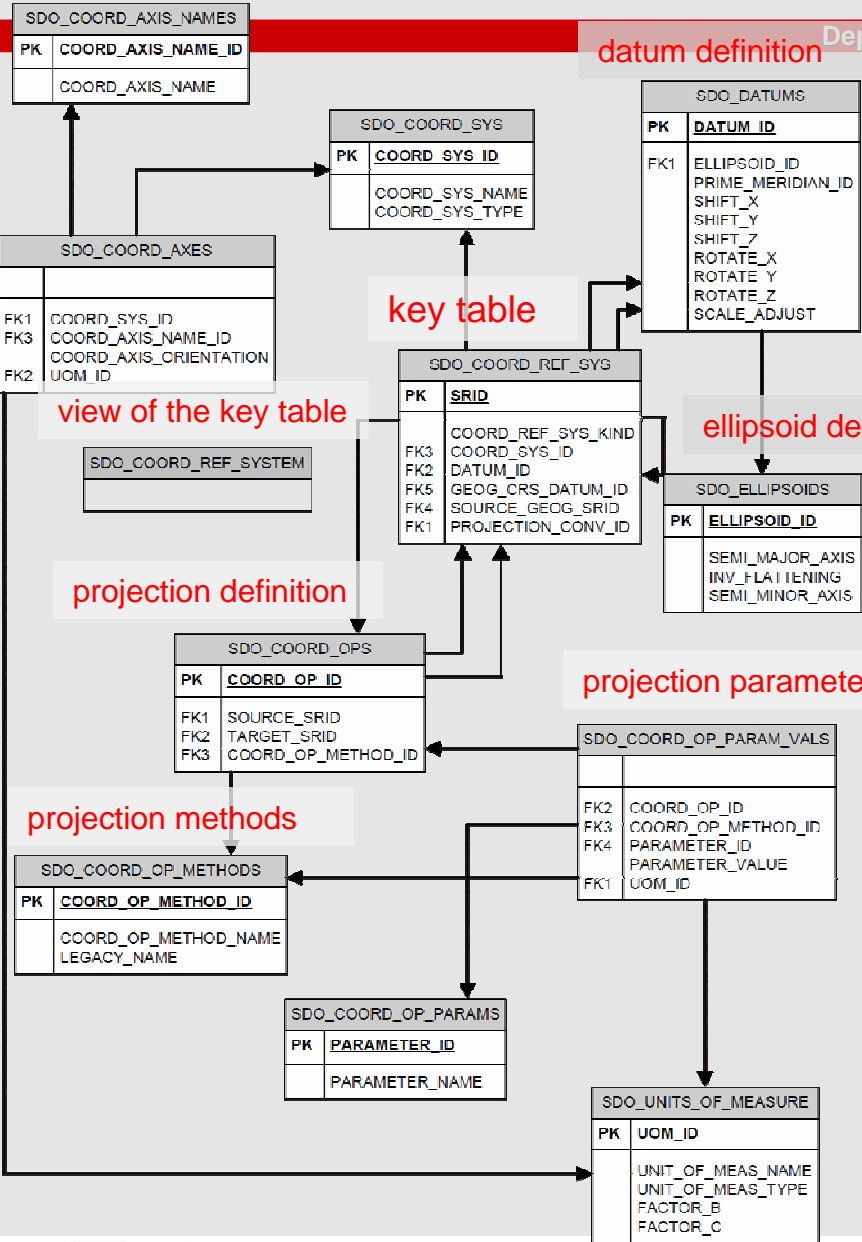
SRID of the defined ETRS89 system

Table with Soldner Berlin coordinates in the SDO_Geometry

- ▶ That results in a table with three columns
 - Point_number (out of the Soldner Berlin table)
 - X (ETRS89 coordinates in UTM)
 - Y (ETRS89 coordinates in UTM)

- This presentation will explain stepwise how to set your own user defined system within Oracle
 - ▶ Data model in Oracle Spatial
 - ▶ Features of the local system in Berlin
 - ▶ Estimation of the datum parameter
 - ▶ SQL- statements to set a special local Soldner Berlin System within Oracle
 - ▶ SQL- statements to use special local Pulkovo 1942 System within Oracle
 - ▶ Conclusion

Data model in oracle spatial

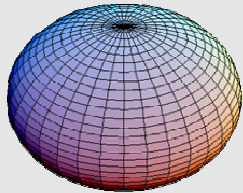


- based on the data model form the European Petroleum Survey Group (EPSG)
- Coordinate systems described in an Entity-Relationship Model
- The key-table is called SDO_COORDREF_SYS, via foreign keys all needed information is linked to this table

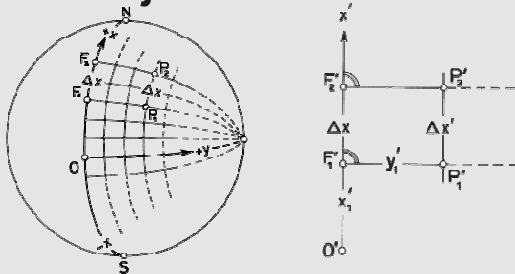
- Oracle classifies different kinds of systems

▶ Vertical for physical height systems

▶ Geodetic systems based on a individual reference surface



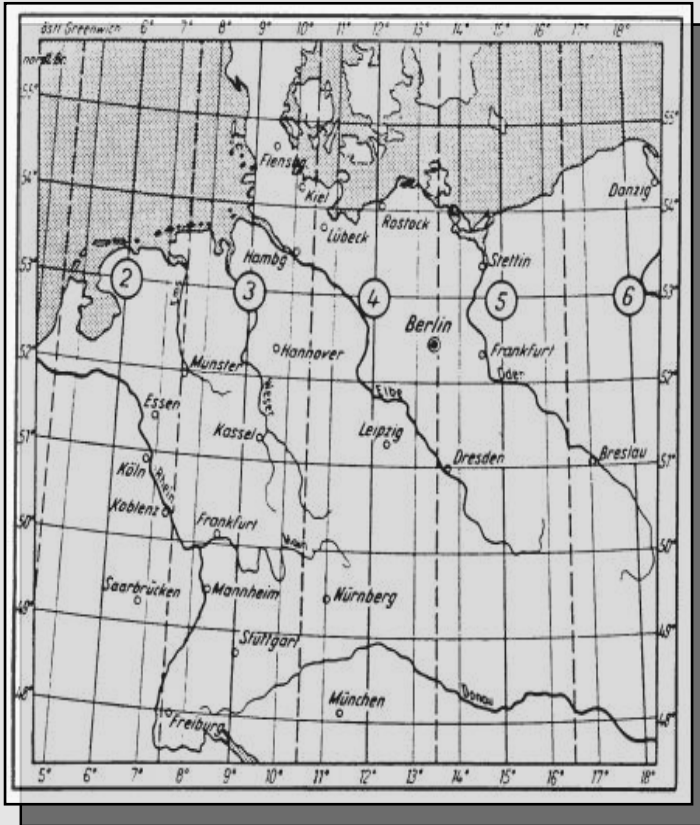
▶ Projected map systems based on geodetic systems (to transform the curved geodetic coordinates in a 2D drawing map)



▶ Compound to define a projected system with physical heights

- Geocentric systems as WGS84 or ETRS89
 - ▶ Typically predefined
- Local systems like Soldner Berlin
 - ▶ Unknown and has to be set into the ER-model
 - ▶ Therefore the projection and datum information are needed

Lets have a closer look to our local system in Berlin.

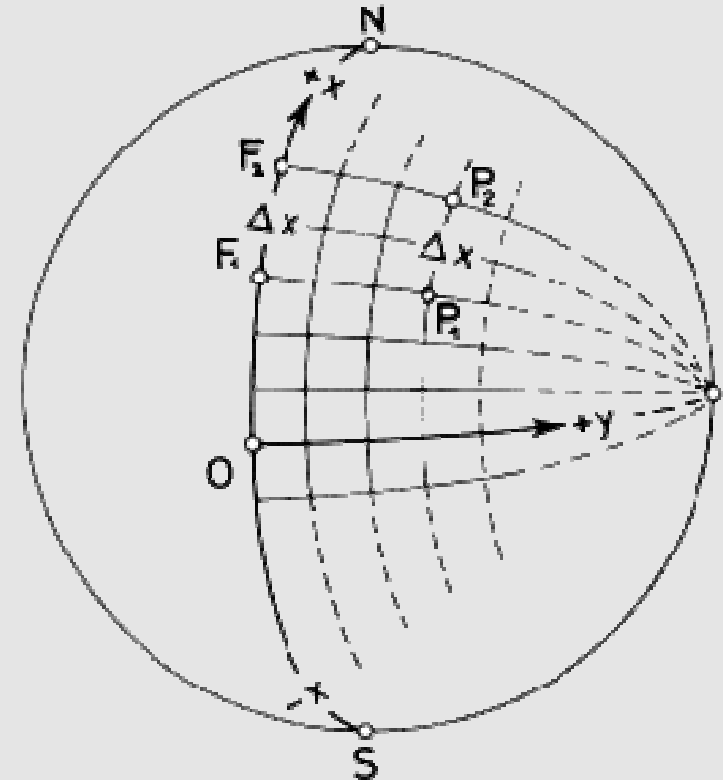
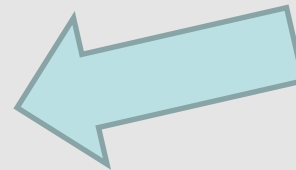
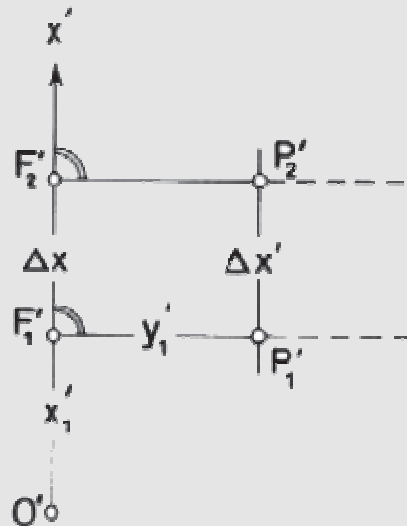


[Source:
<http://www.vermessung-sopart.de/Vermessung-Dateien/image006.jpg>]

- Historical information

- ▶ The geoinformation in northern Germany was in the 18th and 19th century represented in 42 different soldner projections.
- ▶ With the development in projections the most geodata are represented in transversal cylindrical projections (Gauß-Krüger projection, 3° large zones)
- ▶ Because of the location exactly between two zones the soldner projection is still official in use

- Features of the Soldner/Cassini projection in Berlin
 - ▶ Non-conformal projection
 - ▶ Very easy to use
 - ▶ Mathematically clear defined



Features of the local system in Berlin

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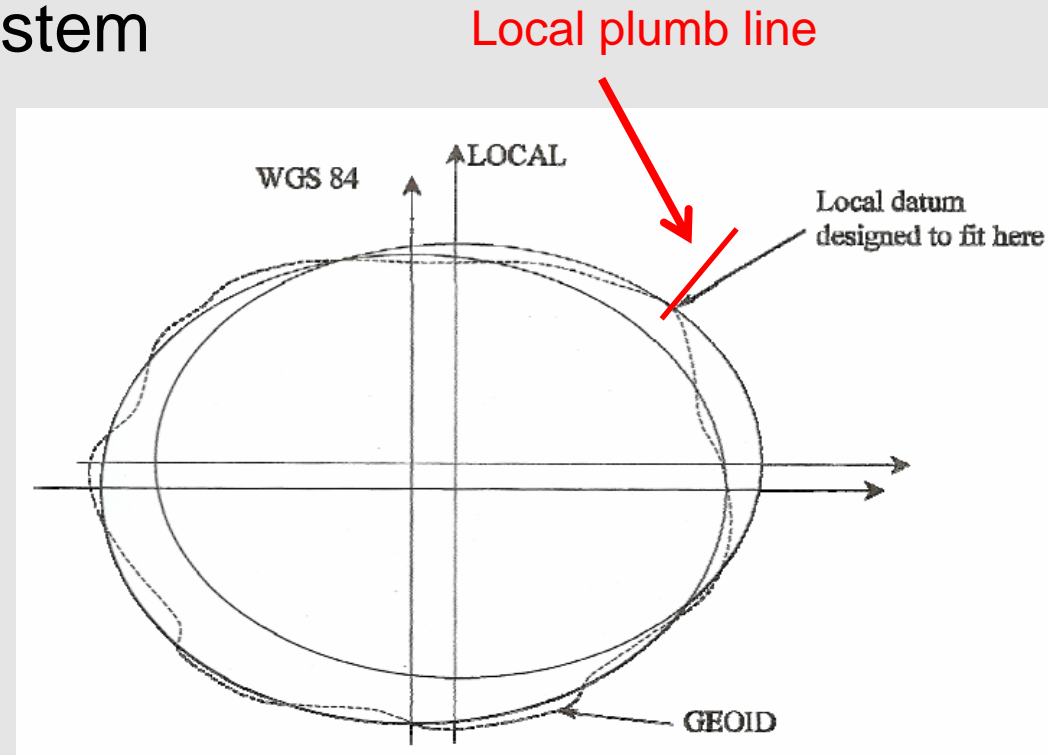
Picture background source: Google maps

Origin realized at the topological point "Müggelberg"

longitude $\lambda = 13^\circ 37' 37.9332''$ East and latitude $\phi = 52^\circ 25' 7.1338''$ North

- Underlying geodetic system

- ▶ Is called “Netz88”
- ▶ Based on the DHDN “Deutsches Hauptdreiecksnetz”
- ▶ DHDN is based on triangulations
- ▶ with a defined vertical deflection in the fundamental point “Rauenberg” as zero
- ▶ different orientation to a geocentric system (different datum)



- With some DHDN points and new local terrestrial and GPS observations a new adjustment solution “Netz 88” was calculated
 - ▶ Without distortions in the data set
 - ▶ Realized on a different unknown reference frame
 - ▶ Different datum parameter from DHDN

How we can estimate such datum parameters?

- ▶ **With an parametric adjustment computation**

- Pre-processing to 3D world coordinates
 - ▶ Step 1
 - Project the coordinates back to the underlying geodetic system
 - Results: 2D geodetic coordinates on the underlying surface
 - ▶ Step 2
 - Calculate the 3D world coordinates with respect to each used ellipsoid
 - Results: two sets of 3D coordinates

Because of the geocentric origin and orientation of the ETRS89 solution, we get the datum parameter of the local system out of the transformation parameter between these both data sets.

- **Assumptions and restrictions**
 - ▶ We used only **2-dimensional Soldner Berlin coordinates**
 - ▶ ETRS89 as **geocentric target system**
 - ▶ **ETRS89 coordinates** were considered as non-stochastic **errorless values**
 - ▶ The **Soldner system** is expected to be nearly **homogeneous**
 - ▶ used were **14 Homologous points** known in the local and target system (evenly distributed over Berlin)

- Used adjustment model
 - ▶ 3D-Helmert transformation

$$\begin{array}{c} \text{Geocentric} \\ \text{coordinates} \end{array} \rightarrow \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}_{ETRS89} = \begin{array}{c} \text{Translation parameter} \\ \begin{pmatrix} \Delta X \\ \Delta Y \\ \Delta Z \end{pmatrix} \end{array} + \begin{array}{c} \text{scale} \\ m \end{array} \begin{array}{c} \text{Rotation matrix} \\ R \end{array} \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}_{\text{local}} \leftarrow \begin{array}{c} \text{3D world} \\ \text{coordinates from} \\ \text{the local system} \end{array}$$

- ▶ **At first** the linear description of the rotation matrix

- Assumptions here: for very small angles $\sin\alpha=\alpha$ and $\cos\alpha=1$
- It easy to implement
- But the solved parameter are **not precise enough**

$$R = \begin{pmatrix} 1 & \alpha_3 & -\alpha_2 \\ -\alpha_3 & 1 & \alpha_1 \\ \alpha_2 & -\alpha_1 & 1 \end{pmatrix}$$

- Good solution brings the use of the full Euler-Rotation-Matrix

$$R = \begin{pmatrix} \cos \beta \cos \gamma & -\cos \gamma \sin \alpha \sin \beta - \cos \alpha \sin \gamma & -\cos \alpha \cos \gamma \sin \beta + \sin \alpha \sin \gamma \\ \cos \beta \sin \gamma & \cos \alpha \cos \gamma - \sin \alpha \sin \beta \sin \gamma & -\cos \gamma \sin \alpha - \cos \alpha \sin \beta \sin \gamma \\ \sin \beta & \cos \beta \sin \alpha & \cos \alpha \cos \beta \end{pmatrix}$$

- ▶ It creates a non lineare adjustment problem were approximated values were needed
 - Translations $T_x=T_y=T_z=0\text{m}$
 - Rotation angles $\alpha=\beta=\gamma=0^\circ$
 - Scale $m=1$

- To **control** the Euler solution and to be **independent from the need of approximated values** we used also quaternion's

$$R = \begin{pmatrix} q_0^2 + q_1^2 - q_2^2 - q_3^2 & 2q_1q_2 - 2q_0q_3 & 2q_0q_2 + 2q_1q_3 \\ 2q_1q_2 + 2q_0q_3 & q_0^2 - q_1^2 + q_2^2 - q_3^2 & -2q_0q_1 + 2q_2q_3 \\ -2q_0q_2 + 2q_1q_3 & 2q_0q_1 + 2q_2q_3 & q_0^2 - q_1^2 - q_2^2 + q_3^2 \end{pmatrix}$$

$$0 = q_0^2 + q_1^2 + q_2^2 + q_3^2 - 1 \quad \text{Condition between the unknowns}$$

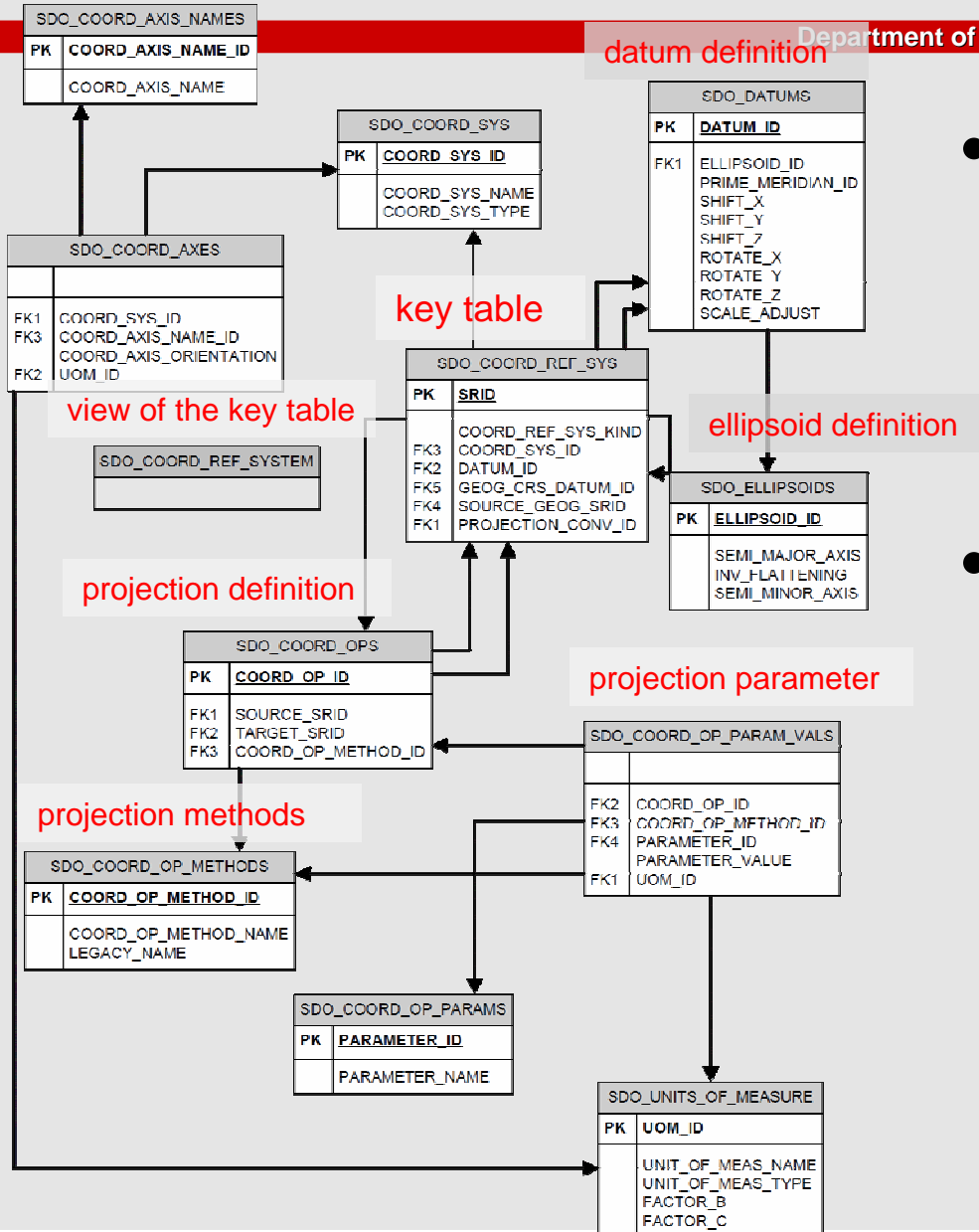
- ▶ Parametric adjustment model with restriction between the unknowns

- Both adjustment solutions results the same parameters after some iterations

Shift in X	675.239155 m
Shift in Y	25.303490 m
Shift in Z	422.544682 m
Rotation in X	-0.717994 sec
Rotation in Y	-1.766241 sec
Rotation in Z	-0.719541 sec
Scale	-0.245916 ppm

- ▶ Oracle use the unit [sec] for the angles and parts per million [ppm] for the scale

SQL- statements to set a special local system



- Presented SQL-statements are in the inverse order
- By setting a system in oracle start defining first with tables without undefined foreign keys

SQL- statements to set a special local system



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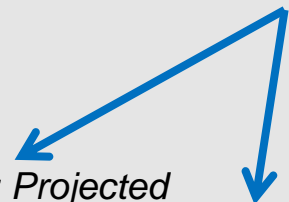
Definition of the projected Soldner Berlin System

```
INSERT
  INTO MDSYS.SDO_COORD_REF_SYSTEM(
    ...
  )
  VALUES(
    7000001,           -- SRID for defined Soldner CS
    'Soldner Berlin', -- COORD_REF_SYS_NAME
    'PROJECTED',     -- COORD_REF_SYS_KIND
    4530,            -- COORD_SYS_ID
    NULL,           -- DATUM_ID
    6000000,        -- GEOG_CRS_DATUM_ID
    7000000,        -- SOURCE_GEOG_SRID
    5000000,        -- PROJECTION_CONV_ID
    ...
  );
```

SDO_COORD_REF_SYS	
PK	SRID
	COORD_REF_SYS_KIND
FK3	COORD_SYS_ID
FK2	DATUM_ID
FK5	GEOG_CRS_DATUM_ID
FK4	SOURCE_GEOG_SRID
FK1	PROJECTION_CONV_ID

Self-proclaimed

predefined



Type: Projected

Type of coordinates System: 4530 – metric (X-North and Y-East)

Datum → NULL, because of 'PROJECTED' non geodetic system

Datum of the underlying geodetic system

ID of the used geodetic CS (Netz88)

Type of projection → Soldner same ID like COORD_OP_ID

Undefined information

SQL- statements to set a special local system



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Definition of the underlying geodetic System "Netz 88"

INSERT

INTO MDSYS.SDO_COORD_REF_SYSTEM(
...

...
)

VALUES(
7000000,

'geodetic net88',

'GEOGRAPHIC2D',

6422,

6000000,

NULL,

NULL,

NULL,
...
);

Undefined information

-- SRID for defined Netz88 CS

-- COORD_REF_SYS_NAME

-- COORD_REF_SYS_KIND

-- COORD_SYS_ID

-- DATUM_ID

-- GEOG_CRSDATUM_ID

-- SOURCE_GEOG_SRID

-- PROJECTION_CONV_ID

Self-proclaimed

predefined

Type: geodetic

Type of coordinates System:
(latitude and longitude)

Datum parameter

NULL-> no other underlying system
exists system

NULL-> no other underlying system
exists system

NULL-> no projection

SDO_COORD_REF_SYS	
PK	SRID
	COORD_REF_SYS_KIND
	COORD_SYS_ID
FK3	DATUM_ID
FK2	GEOG_CRSDATUM_ID
FK5	SOURCE_GEOG_SRID
FK4	PROJECTION_CONV_ID
FK1	

Definition of the projected Soldner Berlin System

INSERT

INTO MDSYS.SDO_COORD_REF_SYSTEM(
...
)

VALUES(
7000001,
'Soldner Berlin',
'PROJECTED',
4530,
NULL,
6000000,
7000000,
5000000,
...
);

-- SRID for defined Soldner CS

-- COORD_REF_SYS_NAME

-- COORD_REF_SYS_KIND

-- COORD_SYS_ID

-- DATUM_ID

-- GEOG_CRG_DATUM_ID

-- SOURCE_GEOG_SRID

-- PROJECTION_CONV_ID

Self-proclaimed

predefined

Type: Projected

Type of coordinates System: 4530 –
metric (X-North and Y-East)

Datum → NULL, because of '
PROJECTED' non geodetic system

Datum of the underlying geodetic
system

ID of the used geodetic CS (Netz88)

Type of projection → Soldner
same ID like COORD_OP_ID

Undefined information

SQL- statements to set a special local system



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Definition of the local Soldner Berlin projection

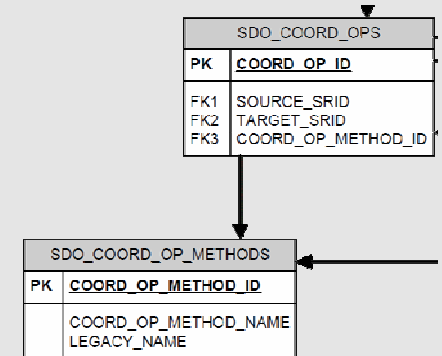
```
INSERT
  INTO MDSYS.SDO_COORD_OPS(
    ...
  )
  VALUES(
    5000000,          -- COORD_OP_ID
    'Soldner Berlin', -- COORD_OP_NAME
    'CONVERSION',    -- COORD_OP_TYPE
    ...
    ...
    9806,            -- COORD_OP_METHOD_ID
    ...
  );
```

projection ID

Name of the projection

Type of operation: translation

predefined projection Method: Cassini



Self-proclaimed

predefined

Parameter Undefined!!!

SQL- statements to set a special local system



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Definition of the local Soldner Berlin projection parameters

How to set these parameters??

SELECT

parameter_id || ': ' ||

legacy_param_name

FROM

sdo_coord_op_param_use

WHERE

coord_op_method_id = **9806**;



Picture background source: Google maps

Result:

8801: Latitude_Of_Origin

8802: Central_Meridian

8806: False_Easting

8807: False_Northing

SQL- statements to set a special local system



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Definition of the local Soldner Berlin projection parameters

How to set these parameters??

SELECT

parameter_id || ': ' ||

legacy_param_name

FROM

sdo_coord_op_param_use

WHERE

coord_op_method_id = **9806**;

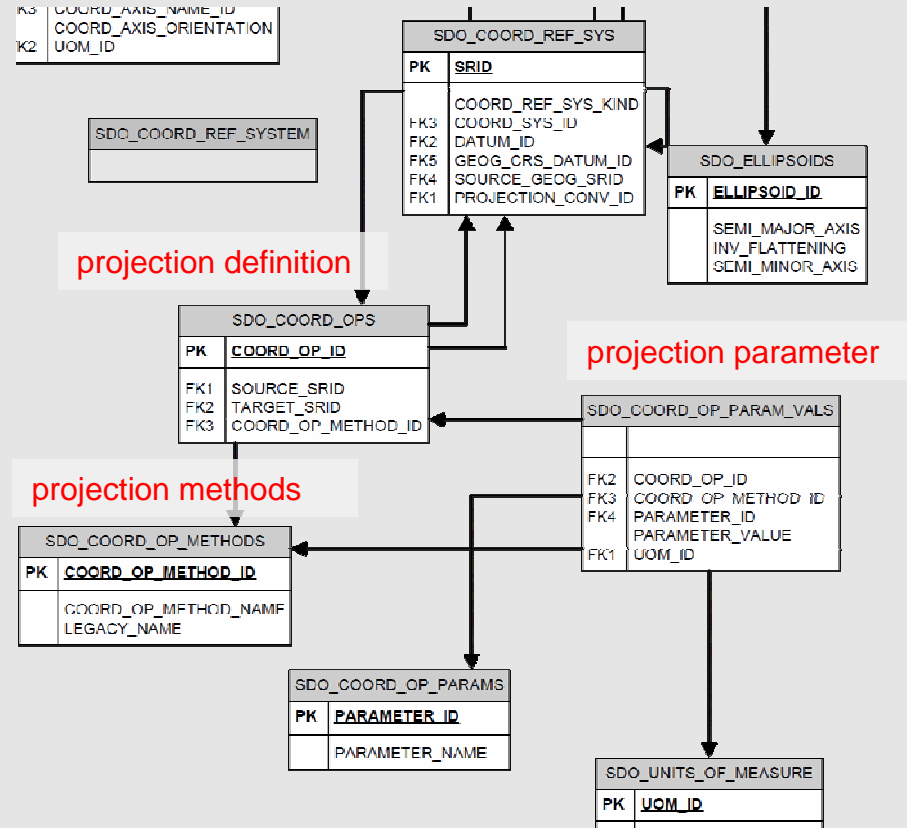
Result:

8801: Latitude_Of_Origin

8802: Central_Meridian

8806: False_Easting

8807: False_Northing



SQL- statements to set a special local system



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Definition of the local Soldner Berlin projection parameters

LATITUDE of origin

```
INSERT
  INTO MDSYS. COORD_OP_PARAM_VALS(
    ...
  )
VALUES(
  5000000,      -- COORD_OP_ID
  9806,         -- COORD_PO_METHOD_ID
  8801,         -- PARAMETER_ID
  52.418648277 -- PARAMETER_VALUE
  10001        -- UOM_ID
  ...
);
```

For every parameter!

projection parameter

SDO_COORD_OP_PARAM_VALS	
FK2	COORD_OP_ID
FK3	COORD_OP_METHOD_ID
FK4	PARAMETER_ID
	PARAMETER_VALUE
FK1	UOM_ID

of the Soldner Berlin
Cassini projection
Parameter ID, 8801: latitude of origin
Value of the parameter
unit of the value

SDO_UNITS_OF_MEASURE	
PK	<u>UOM_ID</u>
	UNIT_OF_MEAS_NAME
	UNIT_OF_MEAS_TYPE
	FACTOR_B
	FACTOR_C

SQL- statements to set a special local system



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Definition of the projected Soldner Berlin System

```
INSERT
  INTO MDSYS.SDO_COORD_REF_SYSTEM(
    ...
  )
  VALUES(
    7000001,           -- SRID for defined Soldner CS
    'Soldner Berlin', -- COORD_REF_SYS_NAME
    'PROJECTED',     -- COORD_REF_SYS_KIND
    4530,            -- COORD_SYS_ID
    NULL,           -- DATUM_ID
    6000000,        -- GEOG_CRG_DATUM_ID
    7000000,        -- SOURCE_GEOG_SRID
    5000000,        -- PROJECTION_CONV_ID
    ...
  );
```

SDO_COORD_REF_SYS	
PK	SRID
	COORD_REF_SYS_KIND
FK3	COORD_SYS_ID
FK2	DATUM_ID
FK5	GEOG_CRG_DATUM_ID
FK4	SOURCE_GEOG_SRID
FK1	PROJECTION_CONV_ID

Type: Projected

Type of coordinates System: 4530 – metric (X-North and Y-East)

Datum → NULL, because of 'PROJECTED' non geodetic system

Datum of the underlying geodetic system

ID of the used geodetic CS (Netz88)

Type of projection → Soldner same ID like COORD_OP_ID

Undefined information

SQL- statements to set a special local system



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Datum Definition of the Soldner Berlin System

INSERT

INTO MDSYS. SDO_DATUMS(

...

)

VALUES(

```

600000,      -- DATUM_ID
'Netz88 (Berlin)', -- DATUM_NAME
'GEODETTIC', -- DATUM_TYPE
8804        -- ELLIPSOID_ID
8901        -- PRIME_MERIDIAN_ID
...         estimated parameter
675.2392    -- SHIFT_X
25.3035,    -- SHIFT_Y
422.5457,   -- SHIFT_Z
-0.71799386, -- ROTATE_X
-1.76624146, -- ROTATE_Y
-0.71954061, -- ROTATE_Z
-0.245916,  -- SCALE
    
```

Name of the datum

Type of the Datum

Ellipsoid ID, 8804: Bessel

Central meridian Greenwich 0°

unit [m]

unit [m]

unit [m]

unit [sec]

unit [sec]

unit [sec]

[ppm]

SDO_DATUMS	
PK	DATUM_ID
FK1	ELLIPSOID_ID PRIME_MERIDIAN_ID SHIFT_X SHIFT_Y SHIFT_Z ROTATE_X ROTATE_Y ROTATE_Z SCALE_ADJUST

SDO_ELLIPSOIDS	
PK	ELLIPSOID_ID
	SEMI_MAJOR_AXIS INV_FLATTENING SEMI_MINOR_AXIS

);

- Oracle now knows the local Soldner Berlin system
- We can create tables with local coordinates
- That table information can be transformed into other Oracle systems only by changing the SRID number.

SELECT

```
P.PKTNUM Point_number,  
SDO_CS.TRANSFORM(P.geom,83033).sdo_point.x X,  
SDO_CS.TRANSFORM(P.geom,83033).sdo_point.y Y,
```

FROM

```
SOLDNER_BERLIN P
```

- Steps for a good transformation with Oracle
 - ▶ **Step 1:** Is the GK 6° System predefined in Oracle Spatial?

```
select SRID, COORD_REF_SYS_NAME
from SDO_COORD_REF_SYSTEM
where COORD_REF_SYS_NAME
like '%GK%Zone 13%';
```

- ▶ Yes it is!

Request:

SRID	COORD_REF_SYS_NAME
82008	GK Zone 13 (Pulkovo 1942)

So you can
use it?

- ▶ **Step 2:** Insert the coordinates as SDO_Geometry with respect to the coordinate system

```
CREATE TABLE GK13_Pulkovo (  
  pktnum NUMBER(10),  
  geom sdo_geometry);
```

```
INSERT INTO user_sdo_geom_metadata  
(TABLE_NAME,COLUMN_NAME,DIMINFO,SRID)  
VALUES
```

```
( 'GK13_Pulkovo', 'GEOM',  
  SDO_DIM_ARRAY( SDO_DIM_ELEMENT('East', 0, 1000000, 0.001),  
  SDO_DIM_ELEMENT('North', 0, 10000000, 0.001)), 82008);
```

Metadata entry to assign oracle the used coordinate system

```
insert into GK13_Pulkovo values( 1, SDO_GEOMETRY(2001, 82008,  
SDO_POINT_TYPE( 4600939.887 , 5800939.300 , NULL), NULL, NULL) );
```

insert some points

```
insert into GK13_Pulkovo values( 2, SDO_GEOMETRY(2001, 82008,  
SDO_POINT_TYPE( 4610938.727 , 5801164.053 , NULL), NULL, NULL) );
```


- ▶ **Step 3:** perform the transformation and compare the result with homological points

```
SELECT P.PKTNUM GK13_TO_UTM48  
to_char(SDO_CS.TRANSFORM( , 99999.999') East,  
to_char(SDO_CS.TRANSFORM( , 99999.999') North  
FROM GK13_Pulkovo P;
```

Well known text of
the definitions

- ▶ If the result is not precise, check the
parameter of the system definition

name of the
system

underlying

```
SELECT wktext FROM cs_srs WHERE srid = 48
```

Request:

```
PROJCS["GK Zone 13 (Pulkovo 1942)",  
GEOGCS ["Pulkovo 1942", DATUM ["Pulkovo 1942",  
SPHEROID ["Krassovsky", 6378245, 298.3]],  
PRIMEM ["Greenwich", 0.000000 ], UNIT ["Decimal Degree", 0.01745329251994330]],  
PROJECTION ["Transverse Mercator"], PARAMETER ["Scale_Factor", 1.000000],  
PARAMETER ["Central_Meridian", 75.000000],  
PARAMETER ["False_Easting", 13500000.000000],  
UNIT ["Meter", 1.0000000000000000]]
```

projection
parameter

► Step 4: Check the datum definition

```
select srid, COORD_REF_SYS_NAME, GEOG_CRS_DATUM_ID from
SDO_COORD_REF_SYSTEM
where COORD_REF_SYS_NAME like '%GK%Zone 13%';
```

Request:

SRID	COORD REF SYS NAME	GEOG CRS DATUM ID
82008	GK Zone 13 (Pulkovo 1942)	10094

► Step 4.1: Check the datum parameter

```
select DATUM_NAME name, ELLIPSOID_ID ell, SHIFT_X DX, SHIFT_Y DY,
SHIFT_Z DZ, ROTATE_X RX, ROTATE_Y RY, ROTATE_Z RZ,
SCALE_ADJUST m from SDO_DATUMS Where DATUM_ID=10094;
```

Request:

name	ellipsoid ID	DX	DY	DZ	Rx	RY	RZ	m
Pulkovo 1942	8031	24	-123	-94	-0,02	0,25	0,13	1,1

↑
Krassovsky
ellipsoid

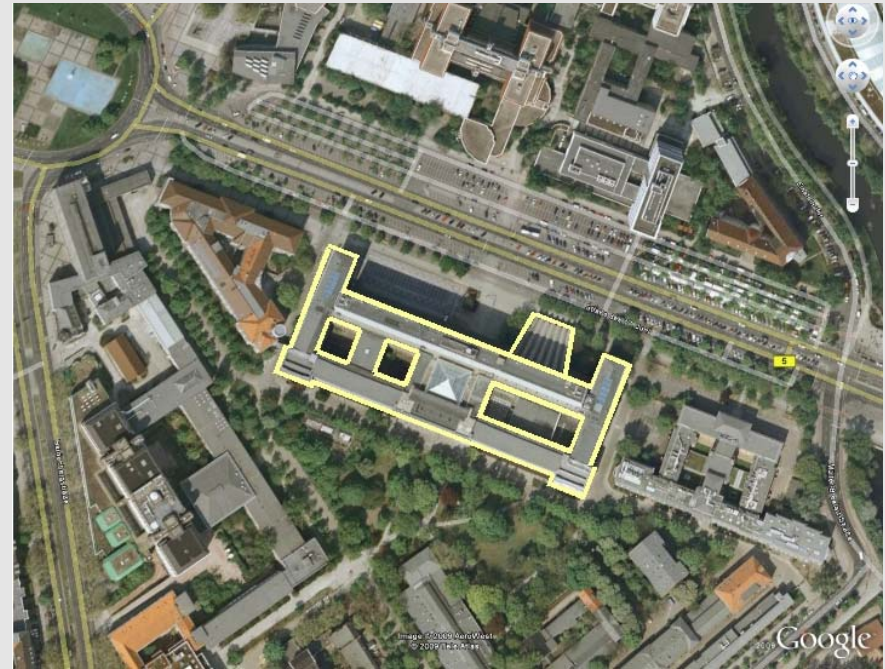
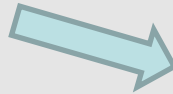
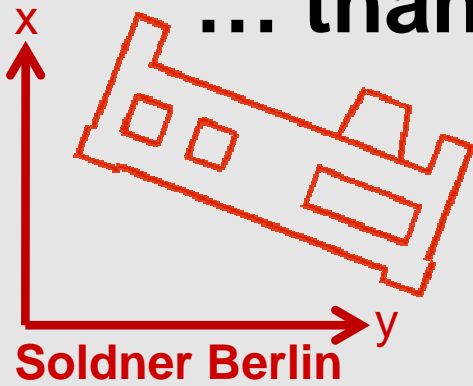
- ▶ **Step 5:** Estimate the new datum parameter with the adjustment computation
- ▶ **Step 6:** Update the datum parameter

```
UPDATE MDSYS.SDO_DATUMS SET  
SHIFT_X    = 26.93176 WHERE DATUM_ID = 10094;  
UPDATE MDSYS.SDO_DATUMS SET  
SHIFT_Y    = -123.92726 WHERE DATUM_ID = 10094;  
...
```

- ▶ **Step 7:** Perform the transformation like at Step 3

- Steps in overview
 - ▶ Collect all information
 - Projections, underlying ellipsoid,...
 - ▶ Estimate the datum parameter by using homological points
 - ▶ Insert or update the new system in Oracle data model
 - ▶ Paste the original coordinates into the SDO-Geometry with the link to the system
 - ▶ Transform the data into different systems only by changing the SRID number

... thank you. Are there any questions?



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