

# **Fibre Optic Sensors: An Overview**

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## **Keywords:**

## **SUMMARY**

Engineering geodesists have the competence to measure the external deformations of structures using automated surveying techniques such as motorized digital levelling systems, autonomous total stations and GPS arrays. The analytical deformation analysis has been fully developed and appropriate software tools are available.

During the past decade, physicists have been developing new sensory capabilities to measure the internal parameters of structures as part of so-called smart civil structures. For civil structures, the primary sensing issues are: (i) measuring the reaction of the structure to external loads, and (ii) determining the internal state-of-health of the structure. For these purposes, small fibre optic sensors (FOS) are embedded and spatially distributed in the structure. FOS have been developed to detect variations in crack formation, strain, temperature and corrosion. A significant advantage of FOS is the ability to multiplex a number of continuous or discrete sensors on one fibre to form a distributed sensor system.

This paper serves the purpose to make engineering geodesists aware of these developments. It provides background information of embedded and distributed FOS using light intensity changes caused by attenuation, scattering and reflection, or phase changes caused by optical path length or refractive index variations.

# 1st FIG International Symposium on Engineering Surveys for Construction Works and Structural Engineering

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## Fibre Optic Sensors: An Overview

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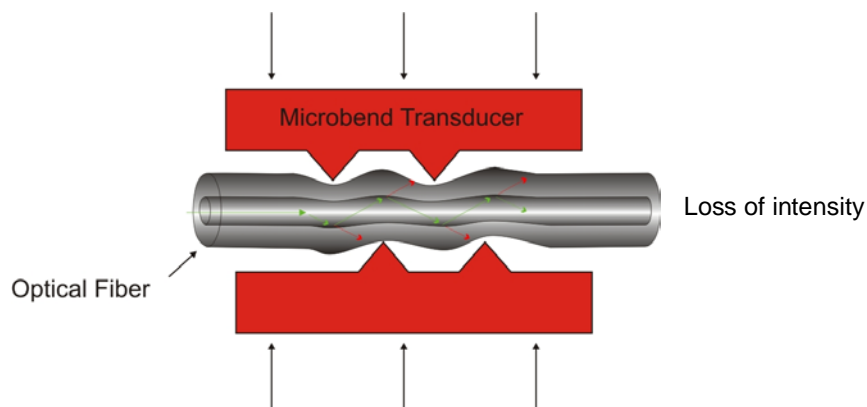


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## Intensity: Microbending-sensor

Pressure and deformation measurements



(Measures RM, 2001)

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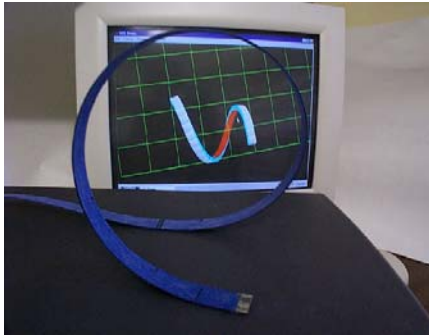
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Session 6 - Fibre Optic Workshop  
Fritz K. Brunner  
TS6.1 Fibre Optic Sensors: An Overview

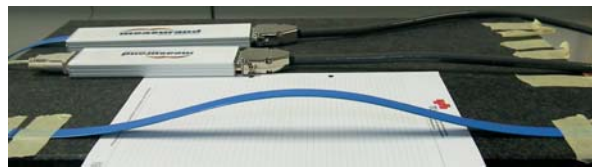
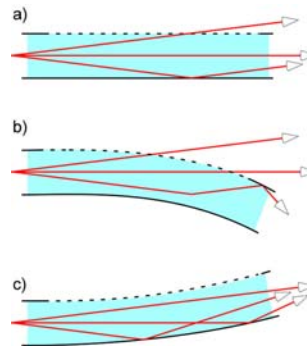
1<sup>st</sup> FIG International Symposium on Engineering Surveys for Construction Works and Structural Engineering  
Nottingham, United Kingdom, 28 June - 1 July 2004

## Curvature measurements

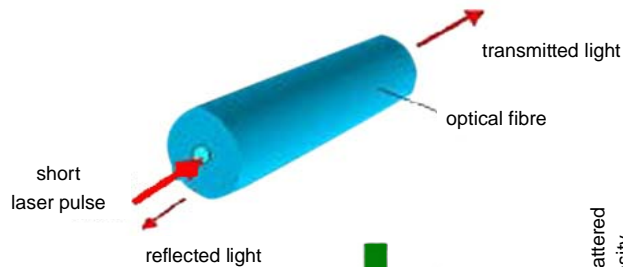
Principle of curvature measurements using FO intensity measurements



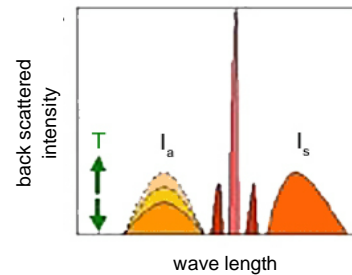
(Commercial realisation „ShapeTape“)



## Raman scattering: Measurement of temperature



$$r_R = \frac{I_a}{I_s} = \left[ \frac{\lambda_s}{\lambda_a} \right]^4 \exp \left\{ - \frac{h \cdot c \cdot \Delta\nu}{k \cdot T} \right\}$$

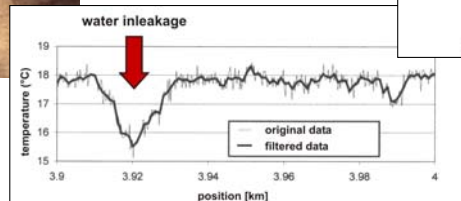
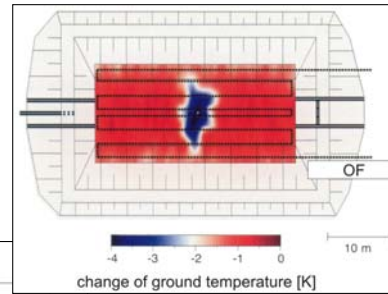
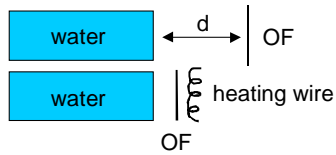


Magnitude ~ 0.8% / K

- Determination of position using propagation time (OTDR)
- Resolution: ~1°C in temperature and ~3 m in position and better using time averaging

## Application: Detection of leakage

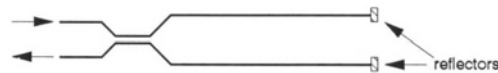
- Gradient method
- Heating method



(Aufleger, 2000)

## Three interferometric designs

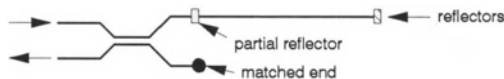
Michelson Interferometer



Mach Zehnder Interferometer

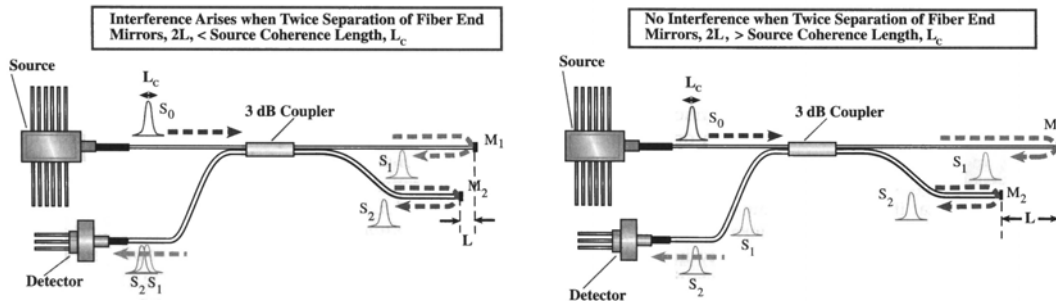


Fabry-Perot Interferometer



(Culshaw B, 1996)

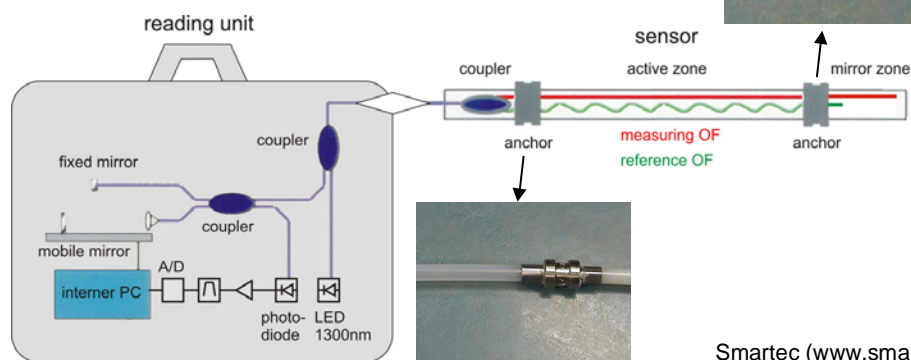
# Low-coherence interferometer



(Measures RM, 2001)

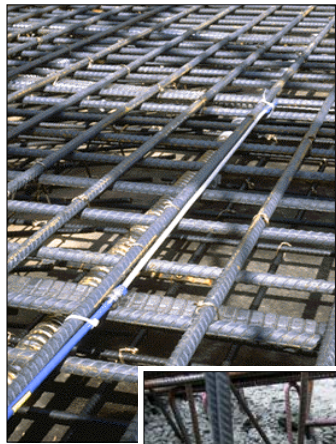
# Strain sensors: SOFO

- Interferometric system
- Absolute measurements using low-coherent light
- Resolution:  $2 \mu\text{m}$
- Length of sensors: 0.2 m - 20.0 m
- Temperature compensated



Smartec (www.smartec.ch)

## SOFO sensor: embedded or external anchoring



## Embedding of SOFO sensors

### Sensor

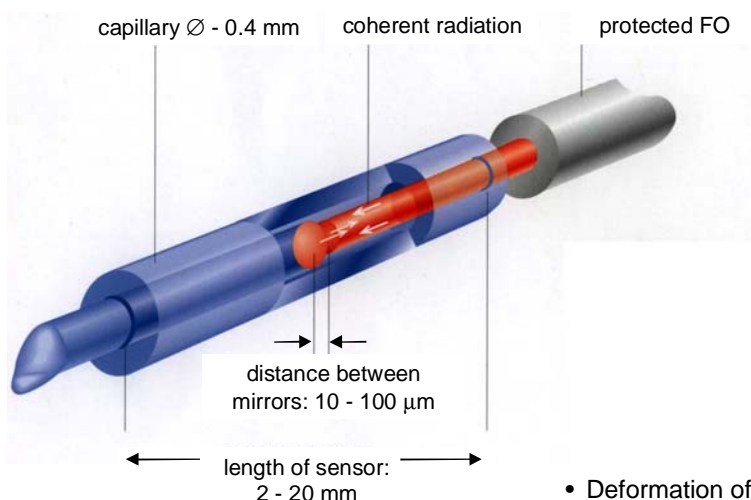
- Iron binder
- Round bar reinforcement

### FO cable

- Mounted below the reinforcement bars
- Loosely fixed with cable ties
- Use of a cabling cabinet



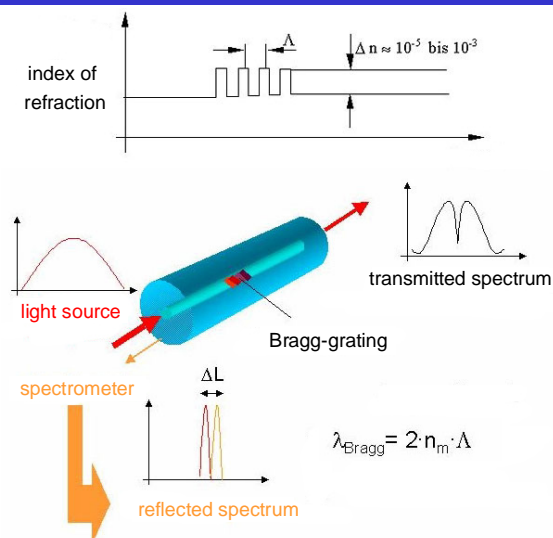
## FO-Fabry-Perot sensor: Strain measurement



- Deformation of the sensor's cavity length causes a change of the distance between the mirrors

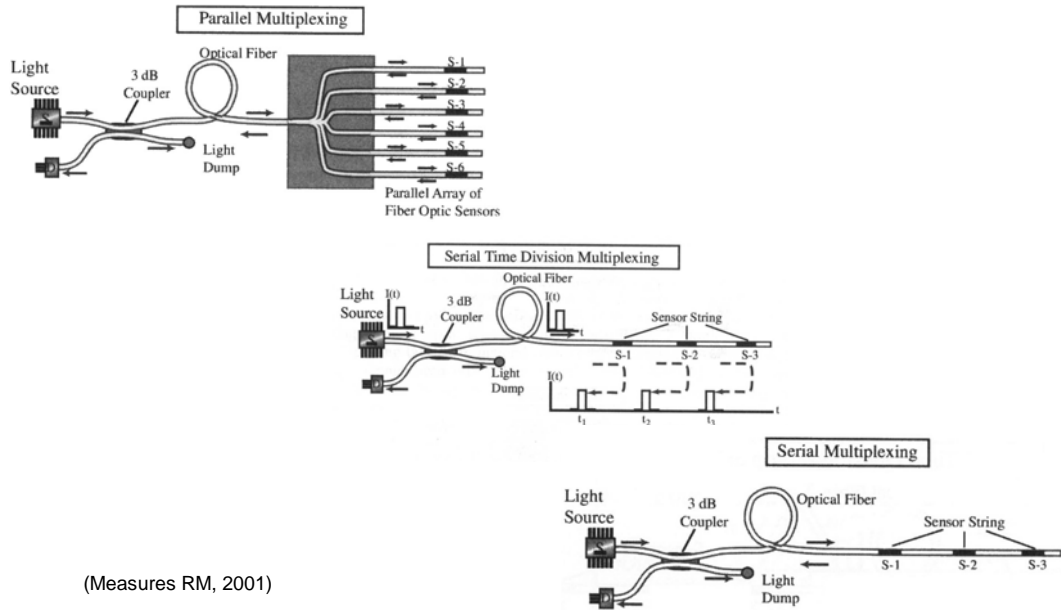
(Habel R, 2003)

## FO Bragg-grating: Strain measurement

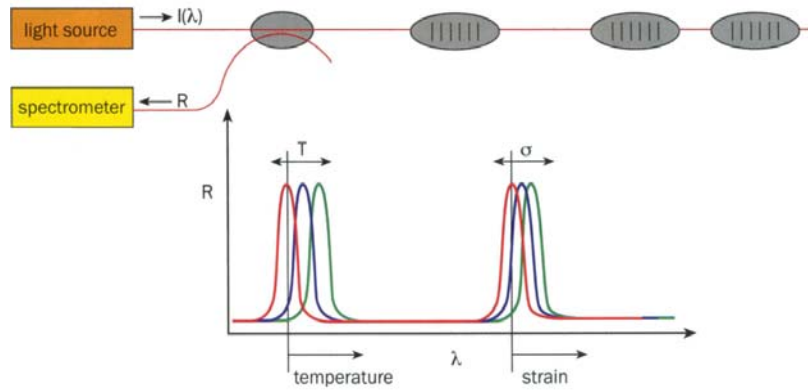


- Several Bragg gratings can be incorporated on one FO

# Multiplexing of sensors



# Multiplexing of FBG: Temperature and strain





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